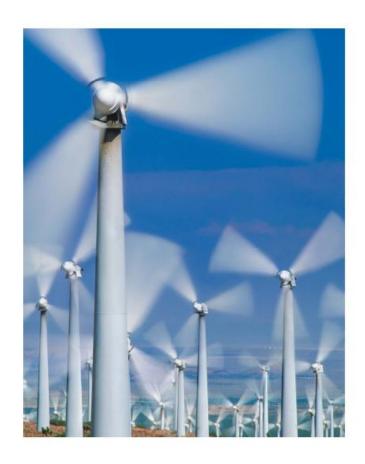
PHYS 270 – SUPPL. #4

DENNIS PAPADOPOULOS FEBRUARY 8, 2011

Chapter 34. Electromagnetic Induction

Electromagnetic induction is the scientific principle that underlies many modern technologies, from the generation of electricity to communications and data storage.



Induction

- E-fields generate B fields (E field in a conductor drives current that creates B)
- Can B fields generate E- fields?
- Yes if the B fields vary in time -Faraday

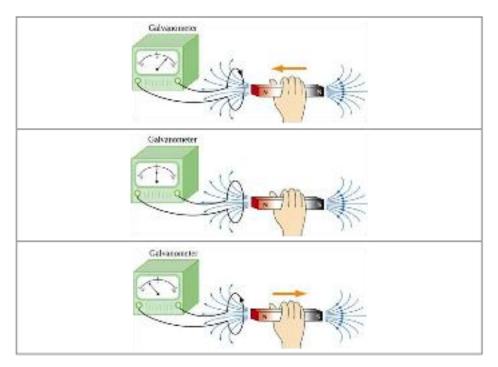


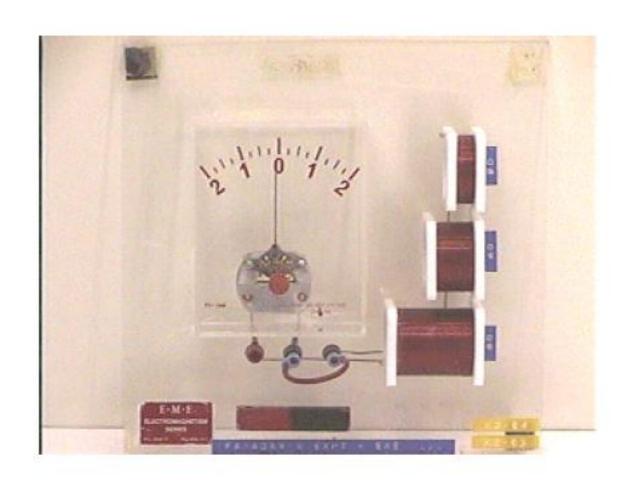
Figure 10.1.1 Electromagnetic induction

- Current flows only if B through the loop is changing
- Faster movement more current
- Current direction changes when either motion or magnet polarity is reversed
- Current linear function of number of turns

Coil behaves as connected to a battery source. EMF

$$EMF \rightarrow \varepsilon = -N \frac{d\Phi_m}{dt}$$

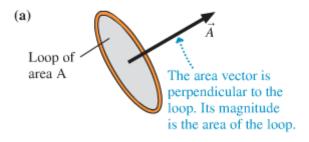
K2-04: FARADAY'S EXPERIMENT - EME SET - 20, 40, 80 TURN COILS

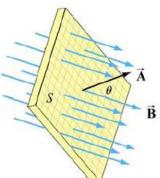


MAGNETIC FLUX CONVENTIONS

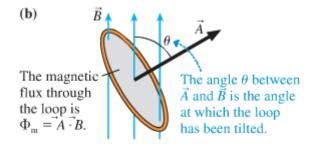
UNIFORM B

FIGURE 34.14 Magnetic flux can be defined in terms of an area vector.





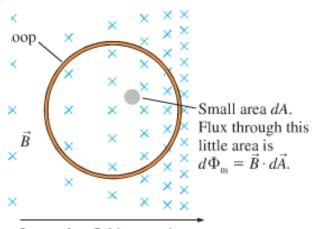
$$\Phi = AB \cos\theta$$



$$\Phi = \vec{A} \bullet \vec{B}$$

NON-UNIFORM B

IGURE 34.16 A loop in a nonuniform nagnetic field.



Increasing field strength

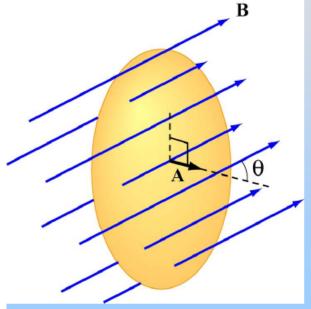
$$d\Phi = \vec{B} \bullet d\vec{A}$$

$$\Phi = \oint \vec{B} \bullet d\vec{A}$$

Units: T-m²=Wb (Weber)

Magnetic Flux Thru Wire Loop

Analogous to Electric Flux (Gauss' Law)



(1) Uniform B

$$\Phi_{B} = B_{\perp} A = BA \cos \theta = \vec{\mathbf{B}} \cdot \vec{\mathbf{A}}$$

(2) Non-Uniform B

$$\mathbf{\Phi}_{B} = \int_{S} \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}}$$

Faraday's Law of Induction

$$\mathcal{E} = -N \frac{d\Phi_B}{dt}$$

A changing magnetic flux induces an EMF

What is EMF?

$$\mathcal{E} = \int \vec{\mathbf{E}} \cdot d\vec{\mathbf{s}}$$

Looks like potential. It's a "driving force" for current

N number of loops in a coil

What about the minus sign?

$\varepsilon = -\frac{d}{dt}(BA\cos\theta) = -\left(\frac{dB}{dt}\right)A\cos\theta - B\left(\frac{dA}{dt}\right)\cos\theta + BA\sin\theta\left(\frac{d\theta}{dt}\right)$ (10.1.5)

How can induce a emf:

- 1.Change magnitude of B
- 2.Change area A
- 3. Change angle θ

Thus, we see that an emf may be induced in the following ways:

(i) by varying the magnitude of \vec{B} with time (illustrated in Figure 10.1.3.)

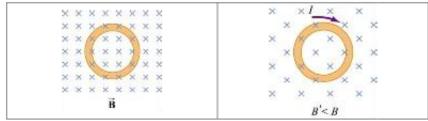


Figure 10.1.3 Inducing emf by varying the magnetic field strength

(ii) by varying the magnitude of \vec{A} , i.e., the area enclosed by the loop with time (illustrated in Figure 10.1.4.)

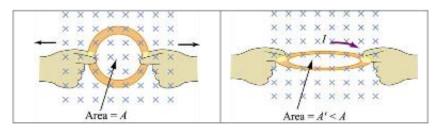


Figure 10.1.4 Inducing emf by changing the area of the loop

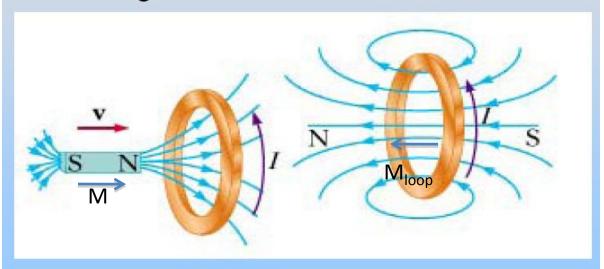
(iii) varying the angle between \vec{B} and the area vector \vec{A} with time (illustrated in Figure 10.1.5.)



Figure 10.1.5 Inducing emf by varying the angle between \vec{B} and \vec{A} .

Minus Sign? Lenz's Law

Induced EMF is in direction that **opposes** the change in flux that caused it



To illustrate how Lenz's law works, let's consider a conducting loop placed in a magnetic field. We follow the procedure below:

- Define a positive direction for the area vector A.
- 2. Assuming that \vec{B} is uniform, take the dot product of \vec{B} and \vec{A} . This allows for the determination of the sign of the magnetic flux Φ_g .
- 3. Obtain the rate of flux change $d\Phi_{\alpha}/dt$ by differentiation. There are three possibilities:

$$\frac{d\Phi_s}{dt}: \begin{cases} > 0 \implies \text{ induced emf } \varepsilon < 0 \\ < 0 \implies \text{ induced emf } \varepsilon > 0 \\ = 0 \implies \text{ induced emf } \varepsilon = 0 \end{cases}$$

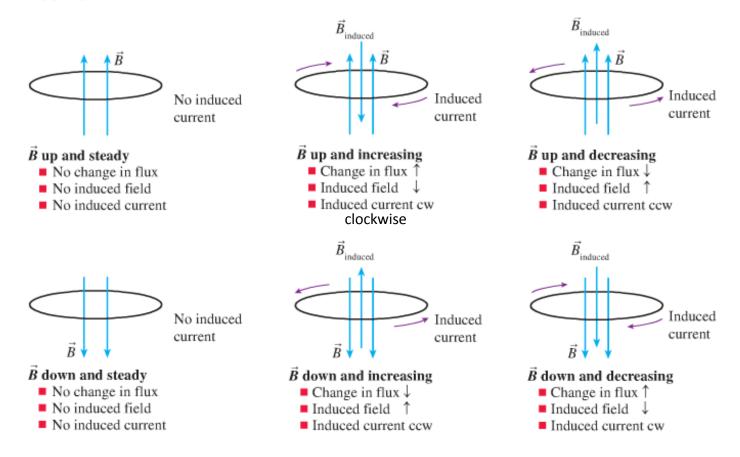
4. Determine the direction of the induced current using the right-hand rule. With your thumb pointing in the direction of \vec{A} , curl the fingers around the closed loop. The induced current flows in the same direction as the way your fingers curl if $\varepsilon > 0$, and the opposite direction if $\varepsilon < 0$, as shown in Figure 10.1.6.



Figure 10.1.6 Determination of the direction of induced current by the right-hand rule

LENZ'S LAW APPLICATION

FIGURE 34.22 The induced current for six different situations.



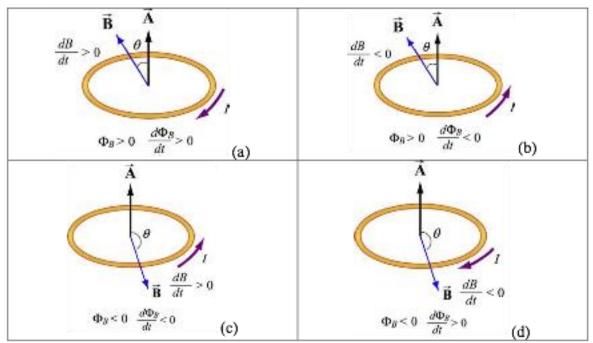


Figure 10.1.7 Direction of the induced current using Lenz's law

The above situations can be summarized with the following sign convention:

$\Phi_{\scriptscriptstyle B}$	$d\Phi_B/dt$	ε	I
+	+	_	_
	_	+	+
_	+	_	_
	_	+	+

The positive and negative signs of I correspond to a counterclockwise and clockwise currents, respectively.

HOW TO CREATE E-FIELDS

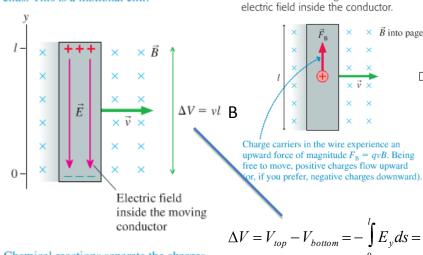
Charge carriers in the wire experience an

upward force of magnitude $F_{\rm R} = qvB$. Being

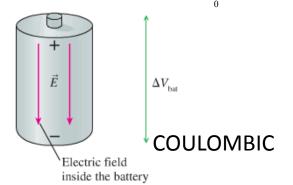
or, if you prefer, negative charges downward).

free to move, positive charges flow upward

(a) Magnetic forces separate the charges and cause a potential difference between the ends. This is a motional emf.

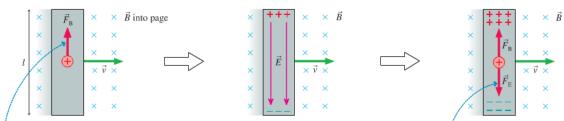


(b) Chemical reactions separate the charges and cause a potential difference between the ends. This is a chemical emf.



NON-COULOMBIC OR INDUCTIVE

FIGURE 34.2 The magnetic force on the charge carriers in a moving conductor creates an electric field inside the conductor.



The charge separation creates an electric field in the conductor. \vec{E} increases as more charge flows.

The charge flow continues until the downward electric force $\vec{F}_{\rm E}$ is large enough to balance the upward magnetic force $\vec{F}_{\rm B}$. Then the net force on a charge is zero and the current ceases.

$$F_{E} = qE$$

$$F_{B} = qvB$$

$$E = vB$$

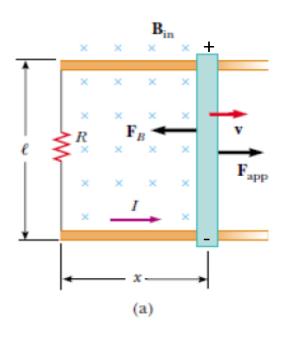
$$EMF, \varepsilon = vlB$$

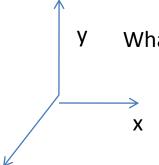
Motional emf

The motional emf of a conductor of length *I* moving with velocity *v* perpendicular to a magnetic field *B* is

$$\mathcal{E} = vlB$$

HOW TO CREATE CURRENTS





Who provides the energy?
What happens if I give the wire a push?

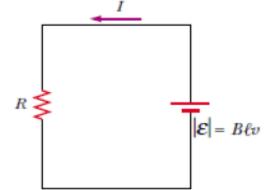
$$I = \varepsilon/R = vlB/R$$

$$\vec{F}_B^z = I(l\hat{e}_y) \times (-B\hat{e}_z) = -IlB\hat{e}_x = -\hat{e}_x(\frac{B^2l^2v}{R})$$

$$m\frac{dv}{dt} = F_B = -\frac{B^2 l^2 v}{R}$$

$$dv/v = -\frac{B^2 l^2 v}{mR} dt = -dt/\tau$$

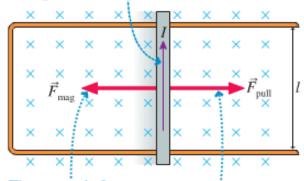
$$|\varepsilon| = B \ell v$$
 $v(t) = v(t=0) \exp(-t/\tau)$



ENERGY – POWER ISSUES

FIGURE 34.6 A pulling force is needed to move the wire to the right.

The induced current flows through the moving wire.



The magnetic force on the current-carrying wire is opposite the motion.

> A pulling force to the right must balance the magnetic force to keep the wire moving at constant speed. This force does work on the wire.

$$dW = \vec{F} \bullet d\vec{s}$$

$$P = dW / dt = \vec{F} \bullet (d\vec{s} / dt) = \vec{F} \bullet \vec{v}$$

To maintain constant $\frac{1}{V}$ need to apply a force

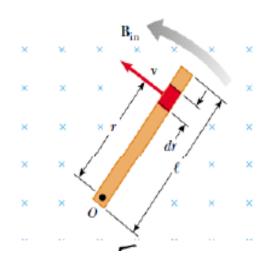
$$ec{F}_{pull} = e_x IlB = e_x (vlB/R)lB$$

$$P_{inp} = \frac{(vlB)^2}{R}$$
 Energy Conservation

$$P_{diss} = I^2 R = \frac{(vlB)^2}{R}$$

A simple generator transforms mechanical power to electrical power

Rotating conducting bar in magnetic field



A conducting bar of length ℓ rotates with a constant angular speed ω about a pivot at one end. A uniform magnetic field **B** is directed perpendicular to the plane of rotation, as shown in Figure 31.11. Find the motional emf induced between the ends of the bar.

Let dq be charge within element dr In equilibrium:

$$F_E = F_B \rightarrow dqdE = dqvB$$
 dE parallel to the bar and across dE
 $v = \omega r \rightarrow dE = \omega rB$
For uniform E - field $\rightarrow |\Delta V| = Ed$
 $dV = dEdr = \omega Brdr$

$$\Delta V = \omega B \int_0^1 rdr = \frac{1^2}{2} \omega B$$

Hydroelectric Power

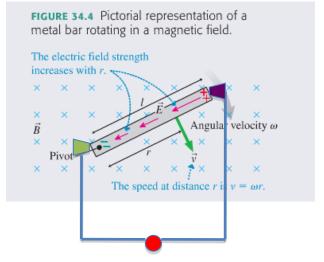
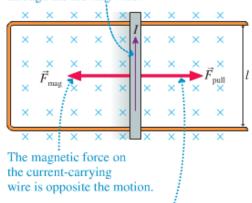


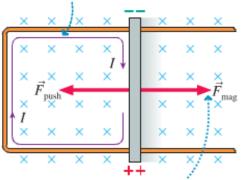
FIGURE 34.6 A pulling force is needed to move the wire to the right.

The induced current flows through the moving wire.



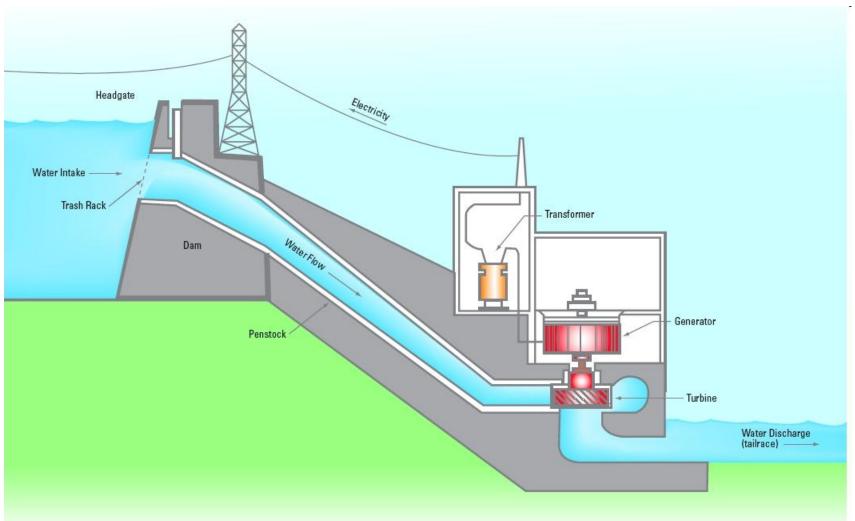
A pulling force to the right must balance the magnetic force to keep the wire moving at constant speed. This force does work on the wire. FIGURE 34.7 A pushing force is needed to move the wire to the left.

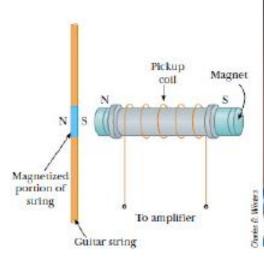
 The magnetic force on the charge carriers is down, so the induced current flows clockwise.



The magnetic force on the current-carrying wire is to the right.

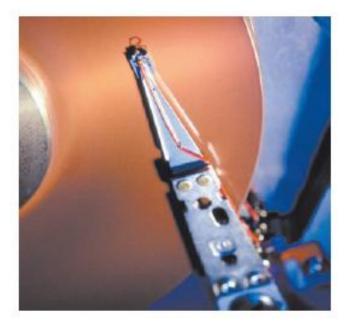
Hydro-Electric Station











Magnetic data storage encodes information in a pattern of alternating magnetic fields. When these fields move past a small pick-up coil, the changing magnetic field creates an induced current in the coil. This current is amplified into a sequence of voltage pulses that represent the 0s and 1s of digital data.

Electric Guitar signal separate magnets strings vibrating string wire coil P20-41

TETHERED SATELLITE SYSTEM

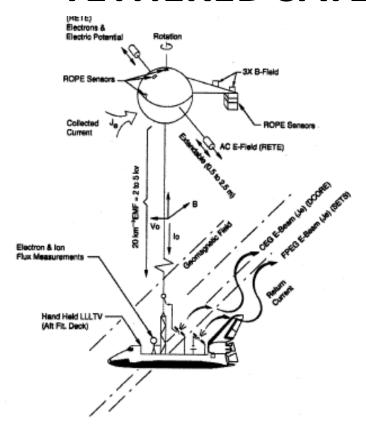


Figure 1.6 TSS Functional Schematic

EMF=vIB= $(8 \text{ km/sec}) (20 \text{ km})(.3 \times 10^{-4} \text{ T})=4.8 \text{ kV}$

R= 4.8 kV/1A=4800 Ohm

P=I(EMF)=4.8 kW

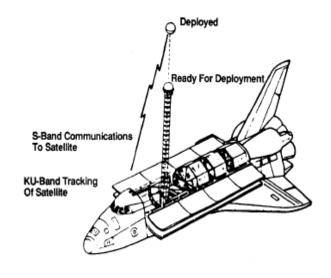


Figure 1.1 TSS-1 Satellite and Tether Attached to 12 Meter Extendible Boom

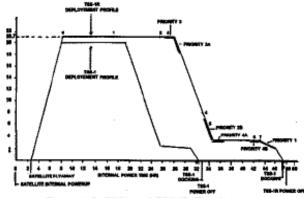


Figure 1.3 TSS1 and TSS1R Timelines